

11-695: AI Engineering

Customizing NNs

LTI/SCS

Spring 2020

- 1 Input
- 2 Auto Differentiation
- 3 Choosing Losses
- 4 Choosing Metrics

- Create a Dataset object from:
 - numpy data (you have done parsing the data into Numpy)
 - file paths to the data (you have just only done collecting paths)
- In a multiple ways:
 - `tf.data.Dataset.from_tensors`
 - `tf.data.Dataset.from_tensor_slices`
 - `tf.data.Dataset.from_generator` - memory efficiency

¹<https://www.tensorflow.org/guide/datasets>

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 - `tf.data.Dataset.from_tensors`
 - `tf.data.Dataset.from_tensor_slices`
 - `tf.data.Dataset.from_generator` - memory efficiency
- If you are sure about data format, use a child class:
 - `tf.data.TextLineDataset`
 - `tf.data.TFRecordDataset`
 - Many more experimentals: Random, CSV, SQL, Kafka, SequenceFile, Kinesis, MachineFiles, LMDB

¹<https://www.tensorflow.org/guide/datasets>

- `tf.data.Dataset.shuffle(buffer_size)`
- `tf.data.Dataset.batch(batch_size)`
- `tf.data.Dataset.repeat(n_epochs)`

tf_data.py

```
1 data = tf.data.Dataset.from_tensor_slices((img_path, img_labels))
2 # doing shuffling, batching, repeating
3
4 # then
5 for batch_data in data:
6     (img, labels) = batch_data
7     # do smth
8
9 # or
10 for (batch_num, (img, labels)) in enumerate(data):
11     # do smth
```

- Iterate the Same as when you work with Python

`tf_custom_data`

```
1 def parse_data(img_path, label_path):
2     # do something to convert paths to data and and labels
3
4 def build_dataset():
5     dataset = tf.data.Dataset.from_tensor_slices((img_paths_tensor, label_paths_tensor))
6     dataset = dataset.map(parse_data, num_parallel_calls=10)
7
8 # then
9 for batch_data in dataset:
10     (img, labels) = batch_data
11     # do smth
12
13 # or
14 for (batch_num, (img, labels)) in enumerate(dataset):
15     # do smth
```

- It is flexible to define your own way of tensorizing your data

- Child classes of `tf.keras.datasets`
- Modules:
 - `boston_housing`: Boston housing price regression dataset.
 - `mnist`: MNIST handwritten digits dataset.
 - `cifar10`: CIFAR10 small images classification dataset.
 - `cifar100`: CIFAR100 small images classification dataset.
 - `fashion_mnist`: Fashion-MNIST dataset.
 - `imdb`: IMDB sentiment classification dataset.
 - `reuters`: Reuters topic classification dataset.

tf.keras.datasets

```
1 mnist = tf.keras.datasets.mnist
2
3 (x_train, y_train), (x_test, y_test) = mnist.load_data()
4 x_train, x_test = x_train / 255.0, x_test / 255.0
5
6 # Add a channels dimension
7 x_train = x_train[..., tf.newaxis]
8 x_test = x_test[..., tf.newaxis]
9
10 train_ds = tf.data.Dataset.from_tensor_slices(
11     (x_train, y_train)).shuffle(10000).batch(32)
12
13 test_ds = tf.data.Dataset.from_tensor_slices((x_test, y_test)).batch(32)
14
15 # train
16 for images, labels in train_ds:
17     train_step(images, labels)
18
19 # test
20 for test_images, test_labels in test_ds:
21     test_step(test_images, test_labels)
```

- Tutorial: [▶ tf.data](#)

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`tf_gtape`

```
1 x = tf.Variable([[1.0, 2.0]]) # float
2 with tf.GradientTape() as tape:
3     tape.watch(x) # x must be a Tensor first, it's auto done
4     # create 'graph' of ops here
5     y = tf.square(x)
6
7 # call gradient() outside the context
8 # <tf.Tensor: id=92, shape=(1, 2), dtype=float32, numpy=array([[2., 4.]], dtype=float32)>
9 dy_x = tape.gradient(y, x)
10
11 dy_x = tape.gradient(y, x) # error! tape is not persistent
```

- Tape is a sequential storage device
- Gradient Tape records gradient in order of operations
 - Under its umbrella of *context*
 - It records ops so that later can calculate grads
 - It costs memory

`tf_gtape_fn`

```
1 def grad(model, x, y):
2     with tf.GradientTape() as tape:
3         loss_value = loss(model, x, y)
4     return tape.gradient(loss_value, model.variables)
5
6 # take grads
7 grads = grad(model, x, y)
8
9 # Backprop: Apply the grads to the model's variables
10 optimizer.apply_gradients(zip(grads, model.variables))
```

- Calculate gradient of the `loss_value` *w.r.t* `x`, `y`
- Normally, avoid `grads calculation` inside `tape's context`
- Control to-watch variables: `watch_accessed_variables=False`

`tf_gtape_fn_2`

```
1 def Model1(tf.keras.Model):
2     ...
3
4 def Model2(tf.keras.Model):
5     ...
6
7 model1 = Model1()
8 model2 = Model2()
9
10 variables = model1.variables() + model2.variables()
11 grads = tape.gradient(loss, variables)
12
13 optimizer.apply_gradients(zip(grads, variables))
```

- Calculate gradient of the `loss_value` *w.r.t* `x`, `y`

`tf_gtape_fn_2`

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- Calculate gradient of the `loss_value` *w.r.t* `x`, `y`
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`tf_gtape_fn_2`

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```

- Calculate gradient of the `loss_value` *w.r.t* `x`, `y`
- Normally, avoid grads *calculation* inside `tape's context`
- Can also have 2 different tapes for different optimization routines (as in GAN)

- Play more with code:
 - ▶ `tf.GradientTape` API
 - Tutorial: ▶ Auto Differentiation
 - GradientTape with ▶ MNIST

- ① Input
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tf.keras.loss

```
1 model.compile(optimizer=...,  
2               loss=tf.keras.losses.SparseCategoricalCrossentropy(),  
3               metrics=...)
```

- Apply a built-in loss from `tf.keras.losses`

tf.keras.loss

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```

- Apply a built-in loss from `tf.keras.losses`
- Convenient way: apply into `model.compile` function

tf.keras_loss_2

```
1 loss_object = tf.keras.losses.SparseCategoricalCrossentropy()
2 train_loss = tf.keras.metrics.Mean(name='train_loss')
3
4 def train_step(images, labels):
5     with tf.GradientTape() as tape:
6         predictions = model(images)
7         loss = loss_object(labels, predictions) # calculate loss
8         gradients = tape.gradient(loss, model.trainable_variables)
9         optimizer.apply_gradients(zip(gradients, model.trainable_variables))
10        train_loss(loss) # averaging
11
12 for epoch in range(EPOCHS):
13     train_loss.reset_states()
14     for images, labels in train_ds:
15         train_step(images, labels)
```

- Apply a built-in loss from `tf.keras.losses`
- Convenient way: apply into `model.compile` function
- Or in a custom (and verbose) way: by a class or function call
- Get output by `result()` function

- MeanSquaredError: $\|\hat{y}_i - y_i\|_2^2$
- MeanAbsoluteError: $|\hat{y}_i - y_i|$
- MeanSquaredLogarithmicError: $\|\log \hat{y}_i - \log y_i\|_2^2$
- MeanAbsolutePercentageError: $100 * \frac{|\hat{y}_i - y_i|}{y_i}$

- BinaryCrossentropy: $-y_i \log(\hat{y}_i) - (1 - y_i) \log(1 - \hat{y}_i)$
- CategoricalCrossentropy:

$$-\sum_{i=1}^C y_i \log \hat{y}_i$$

With the predicted probability for class $i \in \{1, \dots, C\}$ calculated by *softmax* (activation) function for output o_i :

$$\hat{y}_i = \frac{\exp(o_i)}{\sum_{j=1}^C \exp(o_j)}$$

- SparseCategoricalCrossentropy: probably the most used one

- CosineSimilarity: $-\frac{\|\hat{y}\|_2 * \|y\|_2}{n_rows}$ where L2 norm is row-wise.
- KLDivergence: $y * \log \frac{y}{\hat{y}}$
- Hinge: $\max(1 - y * \hat{y}, 0)$
- Huber: MSE if $|y - \hat{y}| \leq \delta$ or $\delta(\text{MAE} - \delta/2)$ otherwise
- LogCosh, Poission, ...

²https://www.tensorflow.org/api_docs/python/tf/keras/losses

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tf.keras.metric

```
1 model.compile(optimizer=...,  
2               loss=tf.keras.losses.SparseCategoricalCrossentropy(),  
3               metrics=tf.keras.metrics.Accuracy())
```

- Apply a built-in loss from `tf.keras.metrics`

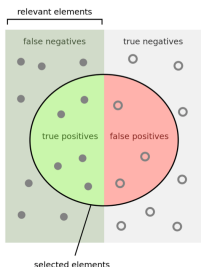
tf.keras.metric

```
1 model.compile(optimizer=...,  
2               loss=tf.keras.losses.SparseCategoricalCrossentropy(),  
3               metrics=tf.keras.metrics.Accuracy())
```

- Apply a built-in loss from `tf.keras.losses`
- Convenient way: apply into `model.compile` function

```
1 train_accuracy = tf.keras.metrics.SparseCategoricalAccuracy(name='train_accuracy')
2
3 @tf.function
4 def train_step(images, labels):
5     with tf.GradientTape() as tape:
6         predictions = model(images)
7         loss = loss_object(labels, predictions)
8         gradients = tape.gradient(loss, model.trainable_variables)
9         optimizer.apply_gradients(zip(gradients, model.trainable_variables))
10
11     train_loss(loss)
12     train_accuracy(labels, predictions)
13
14 for epoch in range(EPOCHS):
15     train_loss.reset_states()
16     train_accuracy.reset_states()
17
18     for images, labels in train_ds:
19         train_step(images, labels)
```

- Other ways: like losses, but for `tf.keras.metrics`
- Also contain the most common losses



How many selected items are relevant?

$$\text{Precision} = \frac{\text{TP}}{\text{TP} + \text{FP}}$$

How many relevant items are selected?

$$\text{Recall} = \frac{\text{TP}}{\text{TP} + \text{FN}}$$

- TrueNegatives, TruePositives, FalseNegatives, FalsePositives
- Precision: $\frac{\text{TP}}{\text{TP} + \text{FP}}$
- Recall: $\frac{\text{TP}}{\text{TP} + \text{FN}}$
- BinaryAccuracy: $\frac{\text{TP} + \text{TN}}{\text{TP} + \text{TN} + \text{FP} + \text{FN}}$

³Those metrics can be generalized for multi-classes as well.

| A | | | B | | | C | | |
|------------|-------|-----|------------|-------|-----|------------|-------|-----|
| TP=63 | FP=28 | 91 | TP=77 | FP=77 | 154 | TP=24 | FP=88 | 112 |
| FN=37 | TN=72 | 109 | FN=23 | TN=23 | 46 | FN=76 | TN=12 | 88 |
| 100 | 100 | 200 | 100 | 100 | 200 | 100 | 100 | 200 |
| TPR = 0.63 | | | TPR = 0.77 | | | TPR = 0.24 | | |
| FPR = 0.28 | | | FPR = 0.77 | | | FPR = 0.88 | | |
| PPV = 0.69 | | | PPV = 0.50 | | | PPV = 0.21 | | |
| F1 = 0.66 | | | F1 = 0.61 | | | F1 = 0.23 | | |
| ACC = 0.68 | | | ACC = 0.50 | | | ACC = 0.18 | | |

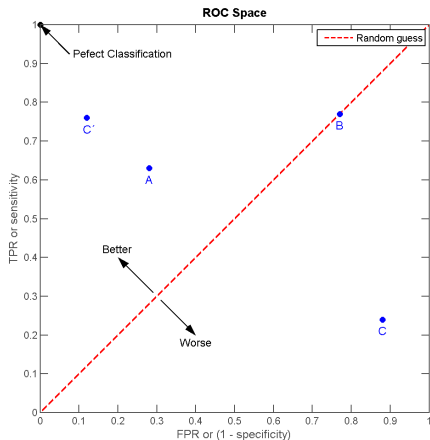
- Consider A, B, and C, which one is the best?

⁴https://en.wikipedia.org/wiki/Receiver_operating_characteristic

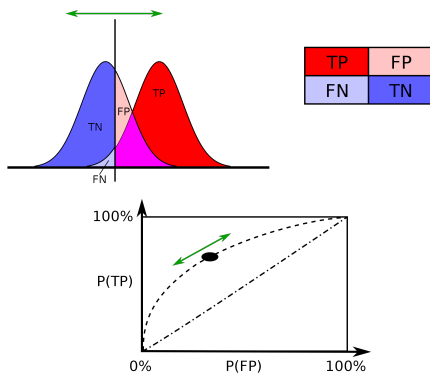
Binary cases: ROC Curve

| A | | | B | | | C | | | C' | | |
|------------|-------|-----|------------|-------|-----|------------|-------|-----|------------|-------|-----|
| TP=63 | FP=28 | 91 | TP=77 | FP=77 | 154 | TP=24 | FP=88 | 112 | TP=76 | FP=12 | 88 |
| FN=37 | TN=72 | 109 | FN=23 | TN=23 | 46 | FN=76 | TN=12 | 88 | FN=24 | TN=88 | 112 |
| 100 | 100 | 200 | 100 | 100 | 200 | 100 | 100 | 200 | 100 | 100 | 200 |
| TPR = 0.63 | | | TPR = 0.77 | | | TPR = 0.24 | | | TPR = 0.76 | | |
| FPR = 0.28 | | | FPR = 0.77 | | | FPR = 0.88 | | | FPR = 0.12 | | |
| PPV = 0.69 | | | PPV = 0.50 | | | PPV = 0.21 | | | PPV = 0.86 | | |
| F1 = 0.66 | | | F1 = 0.61 | | | F1 = 0.23 | | | F1 = 0.81 | | |
| ACC = 0.68 | | | ACC = 0.50 | | | ACC = 0.18 | | | ACC = 0.82 | | |

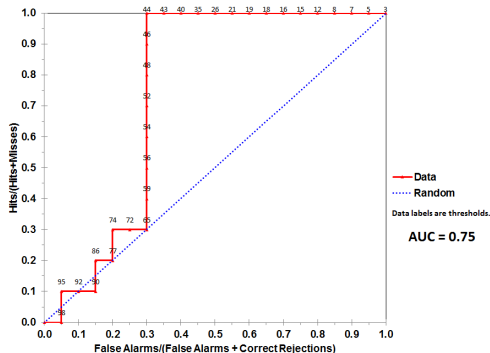
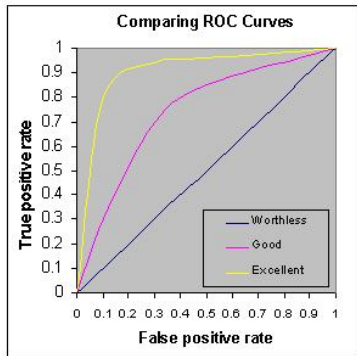
- Consider A, B, and C, which one is the best?
- How about C', the inverse of C?



- How about C', the inverse of C?



- Tradeoff between $TPR = \frac{TP}{TP+FN}$ (Recall) and $FPR = \frac{FP}{FP+TN}$
- These rates are *stable* metrics with classification errors



- AUC: Area under (the ROC) curve, ranges $[0, 1]$
 - AUC is the “aggregation” of ROC over all thresholds
 - A single, stable metric combining others, and so is desirable

- Accuracy: across all classes, can be optionally weighted, for scalars
- CategoricalAccuracy: general cases, for one-hots labels
- SparseCategoricalAccuracy: for scalar labels
- TopKCategoricalAccuracy: for $k > 1$
- SparseTopKCategoricalAccuracy: for scalar labels

⁵ More: https://www.tensorflow.org/api_docs/python/tf/keras/metrics